### <span id="page-0-0"></span>Introduction to Machine Learning Ensemble Learning

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October 28, 2024

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- Consider a set of classifiers  $h_1, ..., h_L$
- $\bullet$  Idea: construct a classifier  $H(x)$  that combines the individual decisions of  $h_1, ..., h_L$ 
	- e.g. could have the member classifiers vote
	- e.g. could use different members for different regions of the instance space
	- works well if the members each have low error rates
- Successful ensembles require diversity
	- Classifiers should make different mistakes
	- Can have different types of base learners

#### Practical Application: Netflix Prize

- Goal: predict how a user will rate a movie
	- Based on the user's ratings for other movies
	- and other people's ratings
	- with no other information about the movies
- This application is called "collaborative filtering"
- $\bullet$  Netflix Prize: \$1M to the first team to do 10% better than the Netflix' system (2007-2009)
- Winner: Bellkor's Pragmatic Chaos
	- An ensemble of more than 800 rating systems



## Combining Classifiers: Averaging

• Final hypothesis is a simple vote of the members



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## Combining Classifiers: Weighted Averaging

Coefficients of individual members are tuned using a validation set



## Combining Classifiers: Gating

- Coefficients of individual members depend on the input
- Train gating function via the validation set



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## Combining Classifiers: Stacking

- Predictions of the first layer used as input to the second laer
- Train the second layer on the validation set





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## Manipulating the Training Data

#### • Bootstrap replication

- Given *n* training examples, construct a new training set by sampling *n* instances with replacement
- Exclude about 30% of the training instances
- Bagging
	- Create bootstrap replicates of the training set
	- Train a classifier (e.g. a decision tree) for each replicate
	- Estimate classifier performance using out-of-bootstrap data
	- Average output of all classifiers
- Boosting
	- (in just a minute ...)

## Manipulating the Features

- Random Forest
	- Construct decision trees on bootstrap replicas
		- Restrict the node decisions to a small subset of features picked randomly for each node
	- Do not prune the rees
		- Estimate tree performance on out-of-bootstrap data
	- Average the output of all trees



# Boosting

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- Developed by Freund & Schapire in 1997
- A meta-learning algorithm with great theoretical and empirical performance
- Turns a base learner (e.g. "weak hypothesis") into a high performance classifier
- Create an ensemble of weak hypotheses by repeatedly emphasizing mispredicted instances

- (Informal) A weak learner is a learning algorithm that outputs a hypothesis (e.g. a classifier) that performs slightly better than chance.
	- e.g. it predicts the correct label with probability 0.51 in binary label case
- We are interested in weak learners that are computationally efficient
	- Decision tree
	- Even simpler decision stumps: Decision trees with a single split

#### Weak Classifiers

• Suppose these are the data



These weak classifiers, which are decision stumps, consist of the set of horizontal and vertical half-spaces.



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## Weak Classifiers

- A single weak classifier is not capable of making the training error small
- But if we can guarantee that it performs slightly better than chance
- Using it with AdaBoost gives us a universal function approximator



Now let's see how AdaBoost combines a set of weak classifiers in order to make a better ensemble of classifiers...

#### The size of a point or instance represents the instance's weight

1: Initialize a vector of *n* uniform weights  $\mathbf{w}_1$ 

2: for  $t = 1, ..., T$ 

- $3:$ Train model  $h_t$  on X, y with weights  $\mathbf{w}_t$
- $4:$ Compute the weighted training error of  $h_t$

5: Choose 
$$
\beta_t = \frac{1}{2} \ln \left( \frac{1 - \epsilon_t}{\epsilon_t} \right)
$$

Update all instance weights:  $6:$ 

 $w_{t+1,i} = w_{t,i} \exp(-\beta_t y_i h_t(\mathbf{x}_i))$ 

- Normalize  $\mathbf{w}_{t+1}$  to be a distribution  $7:$
- 8: end for
- 9: Return the hypothesis

$$
H(\mathbf{x}) = \text{sign}\left(\sum_{t=1}^{T} \beta_t h_t(\mathbf{x})\right)
$$



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7: Normalize 
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 to be a distribution

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- $\beta_t$  measures the importance of  $h_t$
- if  $\epsilon_t \leq 0.5$  then  $\beta_t \geq 0$  (can trivially gurantee)
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h_t
$$
 on  $X, y$  with weights  $\mathbf{w}_t$ 

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 $\leftarrow$   $\Box$   $\rightarrow$ 

- Weights of correct predictions are multiplied by  $e^{-\beta t} \leq 1$
- Weights of incorrect predictions are multiplied by  $e^{\beta t} \ge 1$ 
	- 1: Initialize a vector of *n* uniform weights  $\mathbf{w}_1$

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#### $\bullet$  Note: resized points in the illustration are not necessarily to scale with  $\beta_t$

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 $\begin{array}{c} \leftarrow \quad \quad \text{if} \quad \$ 

#### • Final model is a weighted combination of members

- Each member weighted by its importance
- 1: Initialize a vector of *n* uniform weights  $w_1$

2: for  $t = 1, ..., T$ 

- $3:$ Train model  $h_t$  on X, y with weights  $\mathbf{w}_t$
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- Normalize  $\mathbf{w}_{t+1}$  to be a distribution  $7:$
- $8:$  end for

9: Return the hypothesis  $H(\mathbf{x}) = \text{sign}\left(\sum_{t=1}^{T} \beta_t h_t(\mathbf{x})\right)$ 



**INPUT:** training data  $X, y = \{(\mathbf{x}_i, y_i)\}_{i=1}^n$ , the number of iterations  $T$ the number of iterations  $T$ <br>1: Initialize a vector of *n* uniform weights  $\mathbf{w}_1 = \left[\frac{1}{n}, \dots, \frac{1}{n}\right]$ <br>2: for  $t = 1, \dots, T$ Train model  $h_t$  on X, y with instance weights  $\mathbf{w}_t$  $3:$  $\mathbf{w}_{t}$  is a vector of weights  $4:$ Compute the weighted training error rate of  $h_t$ : over the instances at  $\epsilon_t = \sum w_{t,i}$  $i: u_i \neq h_t(\mathbf{x}_i)$ iteration  $t$ Choose  $\beta_t = \frac{1}{2} \ln \left( \frac{1-\epsilon_t}{\epsilon_t} \right)$  $5:$ All points start with equal  $6:$ Update all instance weights: weight  $w_{t+1,i} = w_{t,i} \exp(-\beta_t y_i h_t(\mathbf{x}_i)) \quad \forall i = 1,\ldots,n$  $7:$ Normalize  $\mathbf{w}_{t+1}$  to be a distribution:  $w_{t+1,i} = \frac{w_{t+1,i}}{\sum_{i=1}^{n} w_{t+1,i}}$   $\forall i = 1, \ldots, n$  $8:$  end for 9: Return the hypothesis  $H(\mathbf{x}) = \text{sign}\left(\sum_{t}^{T} \beta_t h_t(\mathbf{x})\right)$  $46$ 

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**INPUT:** training data  $X, y = \{(\mathbf{x}_i, y_i)\}_{i=1}^n$ , the number of iterations  $T$ 1: Initialize a vector of *n* uniform weights  $\mathbf{w}_1 = \left[\frac{1}{n}, \ldots, \frac{1}{n}\right]$ 2: for  $t = 1, ..., T$  $3:$ Train model  $h_t$  on X, y with instance weights  $\mathbf{w}_t$  $4:$ Compute the weighted training error rate of  $h_t$ :  $\epsilon_t = \sum w_{t,i}$ We need a way to weight instances  $i: y_i \neq h_t(\mathbf{x}_i)$ Choose  $\beta_t = \frac{1}{2} \ln \left( \frac{1-\epsilon_t}{\epsilon_t} \right)$ differently when learning the model...  $5:$  $6:$ Update all instance weights:  $w_{t+1,i} = w_{t,i} \exp(-\beta_t y_i h_t(\mathbf{x}_i)) \quad \forall i = 1, \ldots, n$ 7: Normalize  $\mathbf{w}_{t+1}$  to be a distribution:  $w_{t+1,i} = \frac{w_{t+1,i}}{\sum_{i=1}^{n} w_{t+1,i}}$   $\forall i = 1, \ldots, n$ 8: end for 9: Return the hypothesis  $H(\mathbf{x}) = \text{sign}\left(\sum_{t=1}^{T} \beta_t h_t(\mathbf{x})\right)$ 

#### Training with Weighted Instances

- $\bullet$  For algorithms like logistic regression, can simply incorporate weights  $\psi$ into the cost function
	- Essentially, weigh the cost of misclassification differently for each instance

$$
\mathcal{J}_{\text{reg}}(\boldsymbol{\theta}) = -\sum_{i=1}^{n} w_i \left[ y_1 \log h_{\boldsymbol{\theta}}(\boldsymbol{x}_i) + (1 - y_i) \log (1 - h_{\boldsymbol{\theta}}(\boldsymbol{x}_i)) \right] + \lambda ||\boldsymbol{\theta}_{[1:d]}||_2^2
$$
\n(1)

- $\bullet$  For algorithms that don't directly support instance weights (e.g. decision trees), use weighted bootstrap sampling
	- Form training set by resampling instances with replacement according to  $w$

## Bse Learner Requirements

#### AdaBoost works with "weak" learners

- Should not be complex
- Typically high-bias classifiers
- Works even when the weak learner has an error rate just slightly under 0.5
	- i.e. just slightly better than random
	- Can prove training error goes to 0 in  $O(\log n)$  iterations
- Examples
	- Decision stumps (1 level decision trees)
	- Depth-limited decision trees
	- **•** Linear classifiers

**INPUT:** training data  $X, y = \{(\mathbf{x}_i, y_i)\}_{i=1}^n$ , the number of iterations  $T$ 1: Initialize a vector of *n* uniform weights  $\mathbf{w}_1 = \left[\frac{1}{n}, \ldots, \frac{1}{n}\right]$ 2: for  $t = 1, ..., T$ Train model  $h_t$  on X, y with instance weights  $\mathbf{w}_t$  $3:$  $4:$ Compute the weighted training error rate of  $h_t$ :  $\epsilon_t = \sum w_{t,i}$ Error is the sum the weights of all  $i: u_i \neq h_t(\mathbf{x}_i)$  $\cos \beta_t = \frac{1}{2} \ln \left( \frac{1 - \epsilon_t}{\epsilon_t} \right)$ <br>
Undete all insteads with misclassified instances  $5:$  $6:$ Update all instance weights:  $w_{t+1,i} = w_{t,i} \exp(-\beta_t y_i h_t(\mathbf{x}_i)) \quad \forall i = 1, \ldots, n$  $7:$ Normalize  $\mathbf{w}_{t+1}$  to be a distribution:  $w_{t+1,i} = \frac{w_{t+1,i}}{\sum_{j=1}^{n} w_{t+1,j}}$   $\forall i = 1, ..., n$ 8: end for 9: Return the hypothesis  $H(\mathbf{x}) = \text{sign}\left(\sum_{t=1}^{T} \beta_t h_t(\mathbf{x})\right)$ 

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**INPUT:** train the n This is the same as:<br>  $w_{t+1,i} = w_{t,i} \times \begin{cases} \frac{w}{e^{-\beta_t}} & \text{if } h_t(\mathbf{x}_i) = y_i \\ \frac{e^{-\beta_t}}{e^{\beta_t}} & \text{if } h_t(\mathbf{x}_i) \neq y_i \\ \frac{w}{e^{\beta_t}} & \text{if } h_t(\mathbf{x}_i) \neq y_i \end{cases}$ 1: Initialize a vecto 2: for  $t = 1, ..., T$  $3:$ will be  $\geq 1$  $4:$ Compute the  $\epsilon_t = \sum$  $\sum_{i: u_i \neq h_i \in \mathbf{S}}$  Essentially this emphasizes misclassified instances. Choose  $\beta_t = \frac{1}{2} \mathbf{m} \left( \frac{\epsilon_t}{\epsilon_t} \right)$ 5:  $6:$ Update all instance weights:  $w_{t+1,i} = w_{t,i} \exp(-\beta_t y_i h_t(\mathbf{x}_i)) \quad \forall i = 1,\ldots,n$  $7:$ Normalize  $\mathbf{w}_{t+1}$  to be a distribution:  $w_{t+1,i} = \frac{w_{t+1,i}}{\sum_{j=1}^{n} w_{t+1,j}}$   $\forall i = 1, ..., n$  $8:$  end for 9: Return the hypothesis  $H(\mathbf{x}) = \text{sign}\left(\sum_{t=1}^{T} \beta_t h_t(\mathbf{x})\right)$ 

**INPUT:** training data 
$$
X, y = \{(\mathbf{x}_i, y_i)\}_{i=1}^n
$$
,  
\nthe number of iterations  $T$   
\n1: Initialize a vector of *n* uniform weights  $\mathbf{w}_1 = \left[\frac{1}{n}, \ldots, \frac{1}{n}\right]$   
\n2: **for**  $t = 1, \ldots, T$   
\n3: Train model  $h_t$  on  $X, y$  with instance weights  $\mathbf{w}_t$   
\n4: Compute the weighted training error rate of  $h_t$ :  
\n
$$
\epsilon_t = \sum_{i: y_i \neq h_t(\mathbf{x}_i)} w_{t,i}
$$
\n5: Choose  $\beta_t = \frac{1}{2} \ln \left(\frac{1-\epsilon_t}{\epsilon_t}\right)$   
\n6: Update all instance weights:  
\n $w_{t+1,i} = w_{t,i} \exp(-\beta_t y_i h_t(\mathbf{x}_i)) \quad \forall i = 1, \ldots, n$   
\n7: Normalize  $\mathbf{w}_{t+1}$  to be a distribution:  
\n
$$
w_{t+1,i} = \frac{w_{t+1,i}}{\sum_{j=1}^n w_{t+1,j}} \quad \forall i = 1, \ldots, n
$$
\n8: **end for**  
\n9: **Return** the hypothesis  
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\n
$$
H(\mathbf{x}) = sign\left(\sum_{t=1}^T \beta_t h_t(\mathbf{x})\right)
$$

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**INPUT:** training data  $X, y = \{(\mathbf{x}_i, y_i)\}_{i=1}^n$ , the number of iterations  $T$ 

- 1: Initialize a vector of *n* uniform weights  $\mathbf{w}_1 = \left[\frac{1}{n}, \ldots, \frac{1}{n}\right]$
- 2: for  $t = 1, ..., T$
- Train model  $h_t$  on X, y with instance weights  $\mathbf{w}_t$  $3:$
- $4\cdot$ Compute the weighted training error rate of  $h_t$ :

$$
\epsilon_t = \sum_{i:y_i \neq h_t(\mathbf{x}_i)} w_{t,i}
$$

- Choose  $\beta_t = \frac{1}{2} \ln \left( \frac{1-\epsilon_t}{\epsilon_t} \right)$  $5:$
- $6:$ Update all instance weights:

$$
w_{t+1,i} = w_{t,i} \exp(-\beta_t y_i h_t(\mathbf{x}_i)) \quad \forall i = 1,
$$

 $7:$ Normalize  $\mathbf{w}_{t+1}$  to be a distribution:

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w_{t+1,i} = \frac{w_{t+1,i}}{\sum_{j=1}^{n} w_{t+1,j}} \quad \forall i = 1, \dots, n
$$

- $8:$  end for
- 9: Return the hypothesis

$$
H(\mathbf{x}) = \text{sign}\left(\sum_{t=1}^{T} \beta_t h_t(\mathbf{x})\right)^*
$$

Member classifiers with less error are given more weight in the final ensemble hypothesis

Final prediction is a weighted combination of each member's prediction

- If a point is repeatedly misclassified
	- Each time, its weight is increased
	- Eventually it will be emphasized enough to generate a hypothesis that correctly predicts it
- Successive member hypotheses focus on the hardest part of the instance space
	- Instances with the highest weight are often outliers

- The VC (Vapnik-Chervonenkis) theory originally predicted that AdaBoost would always overfit as  $T$  grew large
	- Hypothesis keeps growing more complex
- In practice, AdaBoost often did not overfit, contradicting the VC Theory
- Also, AdaBoost does not explicitly regularize the model

## Explaining Why AdaBoost Works

- Empirically, boosting resists overfitting
- Note that it continues to drive down the test error even after the training error reaches zero



#### AdaBoost in Practice

#### • Strengths:

- Fast and simple to program
- No parameters to tune (besides  $T$ )
- No assumption on weak learner
- When boosting can fail:
	- **e** Given insufficient data
	- Overly complex weak hypotheses
	- Can be susceptible to noise
	- When there are a large number of outliers

- <span id="page-40-0"></span>Boosted decision trees are one of the best "off-the-shelf" classifiers
	- i.e. no parameter tunning
- Limit member hypothesis complexity by limiting tree depth

**Quote** 

"AdaBoost with trees is the best off-the-shelf classifier in the world" - Breiman

Also, see results by Caruana & Niculescu-Mizil, ICML 2006

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